

Measuring dependence of a space-time ARMAX storage model

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Abstract. We introduce a space-time ARMAX storage model, analogous to the solar thermal energy model considered in Haslett [3] to describe the temperature level in a tank used for the storage of solar energy. For this model we analyze stationarity, max-stability and compute some spatial dependence coefficients.

Keywords. Spatial extreme events; Spatial Dependence Coefficients; Space-time ARMAX model.

1 Introduction

In multivariate and spatial problems attention has often focused on obtaining dependence measures that capture the main characteristics of the dependence structure. For a max-stable stationary random field $\mathbf{X} = \{X_{\mathbf{t}}\}_{\mathbf{t} \in \mathbb{Z}^2}$, with marginal distributions F , the extremal coefficient, $\varepsilon(\mathbf{i}, \mathbf{j})$, defined as

$$P(\max(X_{\mathbf{i}}, X_{\mathbf{j}}) \leq x) = F^{\varepsilon(\mathbf{i}, \mathbf{j})}(x), x \in \mathbb{R},$$

provides information about pairwise extremal dependence of \mathbf{X} (see Schlather and Tawn [4]). This coefficient is related to the upper tail dependence parameter, defined in Sibuya [5] as

$$\lambda(\mathbf{i}, \mathbf{j}) = \lim_{x \rightarrow x_F} P(X_{\mathbf{i}} > x \mid X_{\mathbf{j}} > x),$$

where x_F denotes the upper endpoint of F , through the relation $\lambda(\mathbf{i}, \mathbf{j}) = 2 - \varepsilon(\mathbf{i}, \mathbf{j})$.

Unlike a Gaussian process, the dependence structure of a max-stable process is not completely characterized by its pairwise dependence structure. To overcome this problem Schlather and Tawn [4] extend

the definition of the extremal coefficient to a multivariate setting of any dimension, as follows

$$P\left(\bigvee_{\mathbf{i} \in \mathbf{A}} X_{\mathbf{i}} \leq x\right) = F^{\varepsilon(\mathbf{A})}(x), \quad x \in \mathbf{R}, \mathbf{A} \subseteq \mathbb{Z}^2.$$

This coefficient measures the extremal dependence between the variables indexed by set \mathbf{A} and its simple interpretation as the effective number of independent variables, in the set \mathbf{A} , from which the maximum is drawn has led to its use as a dependence measure in a wide range of practical applications.

When the spatial process \mathbf{X} is isotropic the pairwise extremal dependence measures depend only on the distance $\|\mathbf{i} - \mathbf{j}\|$ between the locations \mathbf{i} and \mathbf{j} considered. Nevertheless, in general, we don't have isotropy and thus need to evaluate the spatial dependence in the several directions of \mathbb{Z}^2 . To attain this we propose a matrix of bivariate tail coefficients defined as

$$\Lambda(T_s^m(\mathbf{i}), \mathbf{i}) = \begin{bmatrix} \lambda(s_4^m(\mathbf{i}), \mathbf{i}) & \lambda(s_3^m(\mathbf{i}), \mathbf{i}) & \lambda(s_2^m(\mathbf{i}), \mathbf{i}) \\ \lambda(s_5^m(\mathbf{i}), \mathbf{i}) & \lambda(s_0^m(\mathbf{i}), \mathbf{i}) & \lambda(s_1^k(\mathbf{i}), \mathbf{i}) \\ \lambda(s_6^m(\mathbf{i}), \mathbf{i}) & \lambda(s_7^m(\mathbf{i}), \mathbf{i}) & \lambda(s_8^m(\mathbf{i}), \mathbf{i}) \end{bmatrix},$$

where for each $\mathbf{i} = (i_1, i_2) \in \mathbb{Z}^2$, $s_j(\mathbf{i})$, $j = 1, 2, \dots, 8$, denote the the neighbors of \mathbf{i} as follows

$$\begin{aligned} s_1(\mathbf{i}) &= (i_1 + 1, i_2), & s_2(\mathbf{i}) &= \mathbf{i} + \mathbf{1}, & s_3(\mathbf{i}) &= (i_1, i_2 + 1), & s_4(\mathbf{i}) &= (i_1 - 1, i_2 + 1), \\ s_5(\mathbf{i}) &= (i_1 - 1, i_2), & s_6(\mathbf{i}) &= \mathbf{i} - \mathbf{1}, & s_7(\mathbf{i}) &= (i_1, i_2 - 1), & s_8(\mathbf{i}) &= (i_1 + 1, i_2 - 1), \end{aligned}$$

$s_j^m(\mathbf{i}) = (s_j \circ \dots \circ s_j)(\mathbf{i})$, k times with $m \geq 1$, $s_0^0(\mathbf{i}) = \mathbf{i}$, $j = 1, 2, \dots, 8$, and $T_s^m(\mathbf{i}) = \{s_j^m(\mathbf{i}) : j = 1, \dots, 8\}$.

Note that, for each $\mathbf{i} \in \mathbb{Z}^2$, $s_0^m(\mathbf{i}) = \mathbf{i}$, $\lambda(\mathbf{i}, \mathbf{i}) = 1$ and, for $m > 1$, we have

$$\lambda(s_j^m(\mathbf{i}), \mathbf{i}) = \lambda(s_t^{m-1}(\mathbf{i}), \mathbf{i}) + \varepsilon(s_t^{m-1}(\mathbf{i}), \mathbf{i}) - \varepsilon(s_j^m(\mathbf{i}), \mathbf{i}), \quad t, j \in \{1, 2, \dots, 8\}.$$

In the next section we introduce a space-time ARMAX storage model for which we analyze stationarity, max-stability and compute some spatial dependence coefficients.

2 A space-time ARMAX storage model

In Haslett [3] the solar thermal energy model

$$X_j = \beta X_{j-1} \vee (\alpha \beta X_{j-1} + Y_j), \quad j \geq 1, \quad 0 \leq \alpha \leq 1, \quad 0 < \beta < 1,$$

was introduced to describe the temperature level in a tank used for the storage of solar energy. This model was further investigated by Daley and Haslett [2], among others. Alpuim [1] studied its extremal behavior for the particular case $\alpha = 0$. We will next present a study of an analogous space-time storage model.

Let $\mathbf{X}^{(0)} = \{X_{(i,0)}\}_{i \geq 1}$ and $\mathbf{Y}^{(j)} = \{Y_{(i,j)}\}_{i \geq 1}$, $j \in \mathbf{N}$, denote independent and stationary random sequences, with, respectively, common univariate marginal distributions H and G , and consider for each subsets $\{i_1, \dots, i_p\} \in \mathbf{N}$ and $\{j_1, \dots, j_p\} \in \mathbf{N}$,

$$H_{(i_1,0), \dots, (i_p,0)}(x_1, \dots, x_p) = P(X_{(i_1,0)} \leq x_1, \dots, X_{(i_p,0)} \leq x_p), \quad (x_1, \dots, x_p) \in \mathbf{R}^p,$$

and

$$G_{(i_1, j_1), \dots, (i_p, j_p)}(x_1, \dots, x_p) = P(Y_{(i_1, j_1)} \leq x_1, \dots, Y_{(i_p, j_p)} \leq x_p), \quad (x_1, \dots, x_p) \in \mathbb{R}^p.$$

We will assume that for each $j \in \mathbb{N}$ the random sequences $\mathbf{Y}^{(j)}$, $j \in \mathbb{N}$, are identically distributed.

Considering the stationary random sequence $\mathbf{X}^{(0)}$ and the stationary random field $\mathbf{Y} = \{Y_{(i, j)}\}_{(i, j) \in \mathbb{N}^2}$ we can now define a max-autoregressive random field through the relation

$$X_{(i, j)} = k(X_{(i, j-1)} \vee Y_{(i, j)}) = k^j X_{(i, 0)} \vee \bigvee_{t=1}^j k^{j-t+1} Y_{(i, t)}, \quad (i, j) \in \mathbb{N}^2, \quad 0 < k < 1.$$

For any locations $\mathbf{r}_1 = (i_1, j_1), \dots, \mathbf{r}_p = (i_p, j_p)$ on \mathbb{N}^2 , and $(x_1, \dots, x_p) \in \mathbb{R}^p$ we have

$$H_{\mathbf{r}_1, \dots, \mathbf{r}_p}(x_1, \dots, x_p) = H_{\mathbf{r}_1 + (0, -1), \dots, \mathbf{r}_p + (0, -1)}\left(\frac{x_1}{k}, \dots, \frac{x_p}{k}\right) \times G_{\mathbf{r}_1, \dots, \mathbf{r}_p}\left(\frac{x_1}{k}, \dots, \frac{x_p}{k}\right).$$

If we consider $i_1 = \dots = i_p = i \geq 1$ fixed, we find the well know Markovian sequence studied in Alpuim [1], for which was shown that for $0 = j_0 < j_1 < \dots < j_p$

$$H_{(i, j_1), \dots, (i, j_p)}(x_1, \dots, x_p) = H\left(\min_{1 \leq s \leq p} \frac{x_s}{k^{j_s}}\right) \prod_{t=1}^p \prod_{s=j_{t-1}}^{j_t-1} G\left(\min_{t \leq m \leq p} \frac{x_m}{k^{j_m-s}}\right). \quad (1)$$

In what follows we shall consider locations $\mathbf{r}_1 = (i_1, j_1), \dots, \mathbf{r}_p = (i_p, j_p)$, on \mathbb{N}^2 , such that $i_{m_1} \neq i_{m_2}$, $m_1, m_2 \in \{1, \dots, p\}$.

The next results give necessary and sufficient conditions for \mathbf{X} to be a stationary max-stable random field.

Proposition 2.1 \mathbf{X} is a stationary random field if and only if, for any locations $\mathbf{r}_1, \dots, \mathbf{r}_p \in \mathbb{N}^2$ and $(x_1, \dots, x_p) \in \mathbb{R}^p$,

$$H_{\mathbf{r}_1, \dots, \mathbf{r}_p}(x_1, \dots, x_p) = H_{\mathbf{r}_1, \dots, \mathbf{r}_p}\left(\frac{x_1}{k}, \dots, \frac{x_p}{k}\right) \times G_{\mathbf{r}_1, \dots, \mathbf{r}_p}\left(\frac{x_1}{k}, \dots, \frac{x_p}{k}\right).$$

If the finite dimension distributions of the sequences $\mathbf{Y}^{(j)}$, $j \geq 1$ associated to the the random field of innovations \mathbf{Y} are multivariate extreme value distributions then \mathbf{Y} is a max-stable random field.

Proposition 2.2 The stationary random field \mathbf{X} is max-stable if and only if \mathbf{Y} is a max-stable random field.

The extremal coefficients of the finite dimension distributions of \mathbf{X} and \mathbf{Y} coincide as shown in the next result.

Proposition 2.3 If both \mathbf{X} and \mathbf{Y} are stationary max-stable random fields then the extremal coefficients of their finite dimension distributions coincide.

From this result we know that $\varepsilon^{\mathbf{X}}(\{\mathbf{r}_1, \dots, \mathbf{r}_p\}) = \varepsilon^{\mathbf{Y}}(\{\mathbf{r}_1, \dots, \mathbf{r}_p\})$ for any locations $\mathbf{r}_1 = (i_1, j_1), \dots, \mathbf{r}_p = (i_p, j_p)$, on \mathbf{N}^2 , such that $i_{m_1} \neq i_{m_2}$, $m_1, m_2 \in \{1, \dots, p\}$. On the other hand, from (1) we obtain $\varepsilon(\{(i, j_1), \dots, (i, j_p)\})$ as follows.

Proposition 2.4 For any choice of $i \geq 1$ and $0 = j_0 < j_1 < \dots < j_p$,

$$\varepsilon(\{(i, j_1), \dots, (i, j_p)\}) = k^{j_1} + \sum_{t=1}^p (1 - k^{j_t - j_{(t-1)}}).$$

We can then conclude that for any point $\mathbf{i} = (i, j) \in \mathbf{N}^2$ it holds

$$\varepsilon(\mathbf{i}, s_3^m(\mathbf{i})) = \varepsilon(\{(i, j), (i, j+m)\}) = 2 - k^m, \quad m \geq 1,$$

and consequently $\lambda(s_3(\mathbf{i}), \mathbf{i}) = k^m$.

Lets now consider $\mathbf{X}^{(0)}$ a stationary Markov chain in discrete time with continuous state space, with distribution function such that

$$H_{(1,0),(2,0)}(x_1, x_2) = \exp(-((-\ln H(x_1))^\delta + (-\ln H(x_2))^\delta)^{1/\delta}), \quad (x_1, x_2) \in \mathbf{R}^2,$$

where $\delta \in [1, +\infty[$ and $H_{(1,0)}(x) = H(x) = \exp(-\exp(-x))$, $x \in \mathbf{R}$.

In this case we obtain

$$\varepsilon(\{(1, 0), (2, 0)\}) = \frac{\ln H_{(1,0),(2,0)}(x, x)}{\ln H(x)} = \frac{-2^{1/\delta} \exp(-x)}{-\exp(-x)} = 2^{1/\delta}, \quad \delta \geq 1,$$

and $\lambda((2, 0), (1, 0)) = 2 - 2^{1/\delta}$, where independence is achieved for $\delta = 1$. The measure matrix of dependence, for $m = 1$, is then given by

$$\Lambda(T_s^1(\mathbf{i}), \mathbf{i}) = \begin{bmatrix} 0 & k & 0 \\ 2 - 2^{1/\delta} & 1 & 2 - 2^{1/\delta} \\ 0 & k & 0 \end{bmatrix}.$$

The computation of the other matrices $\Lambda(T_s^m(\mathbf{i}), \mathbf{i})$, $m \geq 2$, only depends on the computation of $\lambda(T_{s_1}^m(\mathbf{1}), \mathbf{1})$ since we have already shown that, for each $m \geq 1$, $\lambda(T_{s_3}^m(\mathbf{1}), \mathbf{1}) = k^m$. As before we can first obtain the related coefficient $\varepsilon(\mathbf{1}, T_{s_1}^m(\mathbf{1}))$, $m \geq 2$, which can be computed from the dependence function of $(X_{(1,0)}, X_{(m+1,0)})$.

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